

Irrigation, Site-Specific

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INTRODUCTION

Irrigation systems have evolved from flood systems to pressurized sprinkler and trickle systems. In flood irrigation, water is applied to a field in a controlled stream and allowed to flow over the soil surface by gravity, the final distribution being affected by variations in surface slope and water infiltration rates. Well-designed pressurized irrigation systems apply water at sufficiently low rates that it infiltrates with little or no surface movement, thus providing a greater degree of control and improved uniformity of application.

The primary objective of irrigation system design is to apply water (and dissolved chemicals) uniformly over a field planted with a uniform crop, the water requirement being determined primarily by the crop and climate. In recent years, sophisticated control systems have been developed that enable water and chemical application to be tailored to smaller areas if and when it is desirable to do so. The term site-specific irrigation (also known as precision-variable irrigation) refers to the practice of intentionally applying different amounts of water to different areas of a field to optimize crop production, minimize chemical and water use, or reduce environmental concerns. Although site-specific irrigation can be applied with any type of pressurized irrigation system, most of the potential application is with continuous-move sprinkler laterals, primarily center pivots.^[1-5]

DESIGN AND MANAGEMENT OBJECTIVES

Some of the main reasons for site-specific irrigation are the following:

- Avoid watering nonproductive areas such as roads, rock outcrops, canals, ditches, and ponds. Center pivots often traverse these areas that lie within a generally circular area.
- Apply different amounts of water and nutrients to different zones according to crop production capability. Soil depth, salinity, or other soil-related factors may

limit the potential yield and the total water requirement on some soil types.

Apply reduced amounts of water to steep slopes or zones of low infiltration where runoff is difficult to control. A permanent cover crop may be planted in these areas.

Variable soil types within a field may benefit from different amounts of water during certain time periods. Under water-short scenarios, crops on coarse-textured soils having low water holding capacity need small, frequent water applications to avoid water stress, while the crop on finer-textured soils may be able to withdraw stored soil water.

SCALE CONSIDERATIONS

One of the main considerations is determining the minimum size area that must be treated individually.^[6] The cost and complexity of the system escalate rapidly as the treatment area decreases. The wetted radius of the individual sprinkler patterns, the start-stop movement of the lateral, and the accuracy with which the lateral position can be determined all affect the minimum practical differential area. Typically, a 300-m² area is about the smallest desirable unit.

Maps defining soil types, unproductive areas, cropping and fertility patterns are used to define management zones (Fig. 1) requiring different water amounts. These zones should be created from the intersecting areas of only the map parameters that affect the water or chemical requirements.

EQUIPMENT FOR SITE-SPECIFIC IRRIGATION

Sprinkler Laterals

Continuous-move laterals that move in a straight line are called "linears" and those that rotate about a fixed pivot at one end are called "center pivots."^[7] These laterals consist of several rigid spans, typically 40-50 m in length

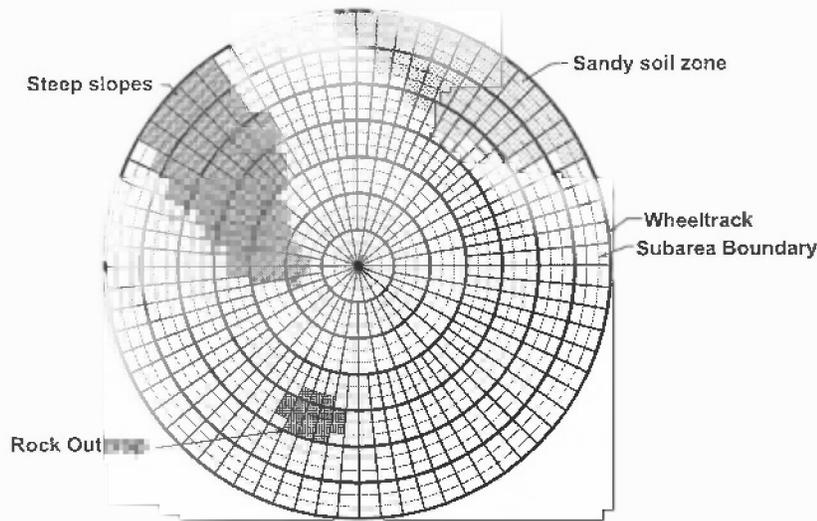


Fig. 1 Schematic of a field irrigated by a 7-span center pivot, with each span subdivided into three segments. Crosshatched areas are special water management zones (photo by Kincaid). (View this art in color at www.dekker.com.)

80 with a total length of about 400 m, although longer laterals 95
 81 are used. The outermost tower controls the rotation speed. 96
 82 The entire lateral is maintained in a nearly straight line by 97
 83 switches at intermediate towers that start and stop the 98
 84 drive motors according to the flex angle between adjacent 99
 85 spans. Center pivots use a transducer (pivot resolver) to 100
 86 determine the position of the first span with an accuracy of 101
 87 about 1° of rotation and a radial coordinate system to 102
 88 determine the position of any point on the lateral relative 103
 89 to the field map at any time. Recently, differential global
 90 positioning system (DGPS) units placed on the outer end
 91 of the lateral have been used to improve the positioning
 92 accuracy of center pivots.

93 Linear laterals use a guidance system to travel on a
 94 predetermined (normally straight) path. A calibrated

ground wheel, fixed ground stakes with a trip switch on
 the lateral, or with a DGPS unit, can determine the lateral
 position along the travel path. Both end towers control the
 travel speed and guidance. Additional error is introduced
 by the guidance system that “steers” the lateral by
 adjusting the relative speed of the end towers, thus
 changing the angle of the lateral relative to the travel path.
 Therefore the positioning accuracy of linears is usually
 less than that of pivots.

104 Sprinkler Equipment and Controls

105 Traveling laterals use sprinkler equipment designed to
 106 discharge a desired amount of water per unit length of



Fig. 2 An on-off spray manifold on a span of a traveling lateral. Note black automatic valve above manifold (photo by Kincaid). (View this art in color at www.dekker.com.)

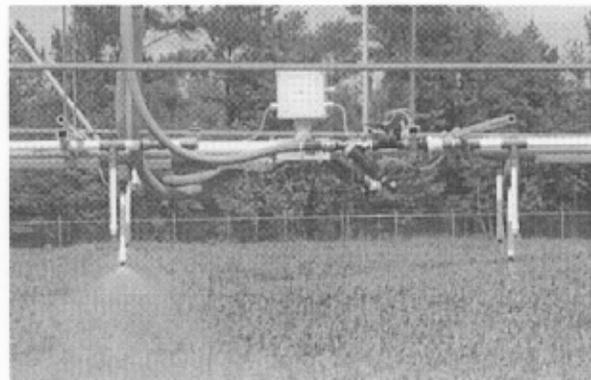
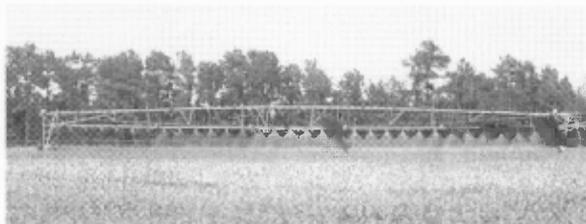


Fig. 3 Close-up of multiple-manifold spray system (photo by Sadler). (View this art in color at www.dekker.com.)

107 lateral. For pivots, the discharge rate increases with 145
 108 distance from the pivot. Sprinklers or spray heads are 146
 109 placed at fixed or variable spacing such that their water 147
 110 application patterns overlap, resulting in nearly uniform 148
 111 water distribution along the lateral. The pattern radii of the 149
 112 most popular spray heads are about 5–8 m. The travel 150
 113 speed of the lateral can be varied to change the water 151
 114 application depth in pie-shaped differential areas under a 152
 115 pivot or in rectangular differential areas under a linear. 153
 116 However, for all other differential areas, sprinkler flows 154
 117 must be varied along the lateral. There are three main 155
 118 methods of accomplishing this.

- 119 1. A variable flow rate sprinkler head uses a fixed nozzle 156
 120 with an insertable pin to produce either a high or low
 121 flow rate.^[8] The pin can be cycled in or out to produce 157
 122 an effective flow rate anywhere between the high and 158
 123 low flow. 159
- 124 2. Automatic valves can be placed on individual 160
 125 sprinklers or groups of sprinklers on manifolds 161
 126 (Fig. 2). Manifold length is usually a fourth to half 162
 127 the span length. One-directional check valves are used 163
 128 on the individual heads to prevent the manifold from
 129 draining when the manifold valve is off. The manifold
 130 valve can be cycled on and off at different time 164
 131 intervals to produce effective application rates be-
 132 tween 0% and 100% of the maximum rate. The cycle
 133 interval must be much less than the time it takes the
 134 full sprinkler pattern to traverse a point on the ground. 165
 135 3. Two or three complete sets of sprinklers designed 168
 136 with different unit flow rates are mounted on the 169
 137 lateral (Figs. 3 and 4). Any combination of the sprin-
 138 kler sets can be turned on one at a time, resulting in
 139 several distinct rates. Two sets provide four possible
 140 rates (e.g., 0, 1/3, 2/3, and 1), and three sets provide
 141 eight possible rates.

142 The variable flow sprinkler (method 1) has not yet
 143 been commercially developed. At the present time, the
 144 on-off manifold (Fig. 2) is likely the most cost-



191 **Fig. 4** A site-specific center-pivot system with selected spray
 192 manifolds off (photo by Sadler). (View this art in color at
 193 www.dekker.com.)

effective configuration, as this involves the least additional equipment.

The computerized control system is normally located at the pivot or inlet end of the lateral.^[9] The computer determines the location of the lateral, adjusts the travel speed, and turns sprinkler control valves on or off according to a predetermined program as the lateral passes over each subarea of the field. Valves are usually electric-solenoid-operated and each requires a separate control wire. Optionally, a code-based control system can send signals to individual valves through a single wire.^[10]

CONCLUSION

New technologies have made precision variable water application technically feasible. Many different scenarios of variable soils, different crops, limited water supplies, and environmental concerns may make site-specific irrigation desirable. Because of the cost and complexity of these systems, economic feasibility will be highly case-dependent.

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